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## 1-1 Introduction

7STARLAKE military computers are based on industry standard Commercial Off-The-Shelf (COTS) open, scalable, modular architecture-technologies that enable prime contractors and system integrators to deploy quickly while meeting size, weight, power and cost (SWaP-C) budgets.

#### **Panel Computer**

7StarLake's Smart Display and Panel Computers are equipped with 6 to 20 programmable function keys made of rugged rubber, allowing configurability based on various mission requirements. These programmable function keys provide convenience and efficiency for users when in critical battle conditions.

#### **Xeon D VMware Workstation**

VMware software powers the world's complex digital infrastructure. The company's cloud, app modernization, networking, security, and digital workspace offerings help battlefield deliver any application on any cloud across any device. SR800 & AV800 series based on Intel Xeon DE platform covering multi-core processor up to 16 cores featured by D-1587 & D-2183IT.

#### **MXM-GPU EDGE Computer**

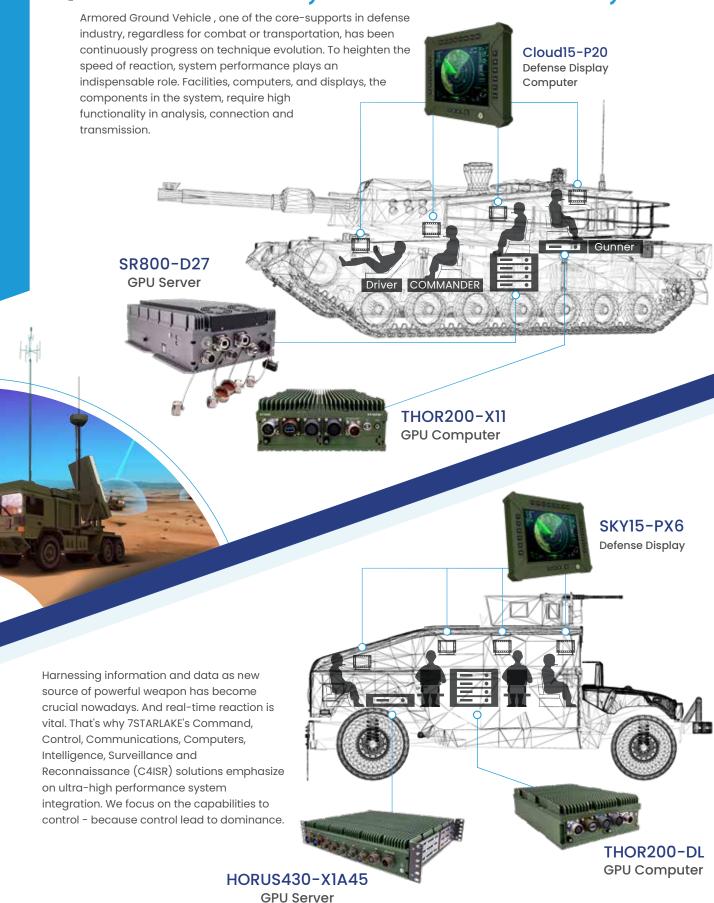
Traditionally, sensors on military vehicles collect massive amounts of battlefield data and store it locally before transporting it for analysis and interpretation by highly sophisticated, remote deep learning systems. Edge GPGPU systems allow extraordinary amounts of data to be collected and processed right on the battlefield in real time.

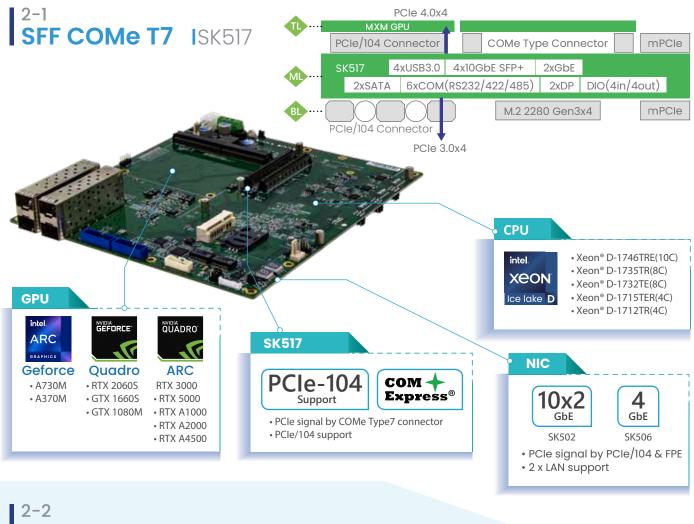
#### **MXM-GPU Rack-Mount Server**

Our HORUS 420 & HORUS 430 series offer the high performance of various NVIDIA QUADRO MXM GPUs paired with the latest Intel Xeon CPUs in a 2U fanless rugged chassis. With patented design in conduction cooled technology, this server series can survive in the harshest environments (MIL-STD-810, vibration up to 5 GRMS and shock up to 40 g).

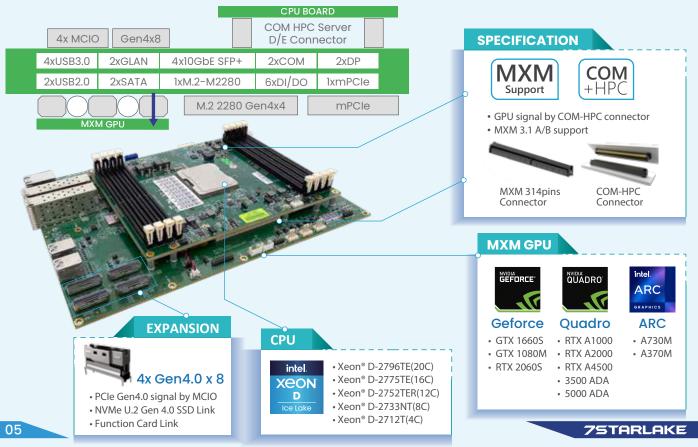


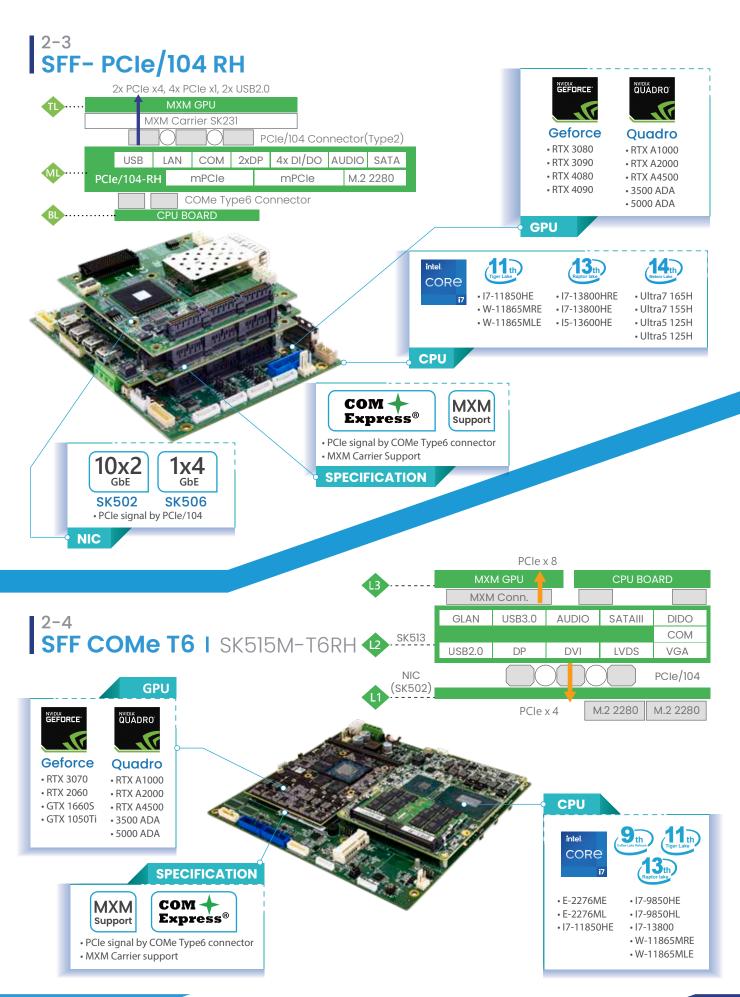
## **Command & Control Systems in Armored Vehicles Systems**











COMe T6 **PCIe / 104** COMe T7









AV600RH-A45

THOR200-X11

THOR200-DL

#### Vibration test (Operating)

Frequency: 20 Hz to 2000 Hz Acceleration: 10 grms Test Axis: X, Y, Z axis Test Time: 30 mins (Each axis)

Total Test Time: 1.5 hrs

#### Frequency: 10 Hz to 500 Hz

Acceleration : 7 grms Test Axis : X, Y, Z axis

Vibration test (Operating)

Test Time: 30 mins (Each axis) Total Test Time : 1.5 hrs

#### Vibration test (Operating)

Frequency: 10 Hz to 500 Hz Acceleration : <u>5</u> grms Test Axis : X, Y, Z axis

Test Time: 30 mins (Each axis) Total Test Time : 1.5 hrs

#### Shock test (Non-Operating mode)

Wave Form: Saw tooth wave Acceleration : 75 grms Duration Time: 6 mS

No. of Shock: 3 times (Each axis) Shock Direction: +Z axis

#### Shock test (Non-Operating mode)

Wave Form: Half Sine Wave Acceleration : 40 grms Duration: 11 mS

No. of Shock: 1 time (Each axis) Shock Direction: +Z axis

#### Shock test (Non-Operating mode)

Wave Form: Half Sine Wave Acceleration : 25 grms Duration: 11 mS

No. of Shock: 1 time (Each axis) Shock Direction: +Z axis

#### MIL-STD 810

The military standard MIL-STD-810 addresses a range of environmental conditions that include: exposure to high and low temperatures plus temperature shock (both operating and in storage), low pressure for altitude testing, rain (windblown and freezing rain), humidity, fungus, salt fog, sand and dust exposure, explosive atmosphere, leakage, and acceleration.

7Starlake's computers are designed to meet the strict standards of MIL-STD 810. When it comes to true ruggedness, MIL-STD-810 standard is considered the upmost principle. Originally established by the US government to simulate how materials would hold up to harsh environments, It provides a series of testing procedures for resistance to shock, vibration, dust, humidity, and extreme temperatures.



#### 1. Vibration

#### MIL-STD-810 Test Method 514.6 **Vibration Procedure IV** Non-Operating

#### MIL-STD-810 Test Method 514.6 **Vibration Procedure III Operating**

Vibration test is conducted to create an environment, in which long-term and high level vibration is simulated. The test is performed with both the system operating/non. Various levels and duration of vibration is simulated in three axis (X, Y, and Z), with up to 7g transitions.

#### 2.Mechanical Shock

#### ▶MIL-STD-810 Test Method 516.6 **Shock-Procedure IV Non-Operating**

#### ▶MIL-STD-810 Test Method 516.6 **Shock-Procedure III Operating**

Mechanical Shock test is conducted to ensure that equipment can withstand drops encountered during handling, transportation, and normal use. The test is performed with both the system operating/non. We expose the system to 3 pulses/direction of sawtooth shock at 100g 11ms. 6 directions for a total of 18 pulses.

#### 3. Temperature Shock

#### ▶MIL-STD-810 Test Method 503.5 Temperature Shock Procedure I-C / Storage (Multi-cycle shocks from constant extreme temperature, From 85° C to -40° C, Three cycles)

Temperature Shock test, also named Thermal Shock test, is to ensure that systems can thrive even in extreme temperature range. We place the system at ambient temperature into chamber at -40°C and stabilize it, then transfer in less than 1 minute to chamber at +85°C and stabilize. Return the system to ambient temperature and perform operational check.

#### **MIL-STD 810**

#### 4. High Temperature

►MIL-STD-810G Test Method 501.5 high Temp (96 hours @75° C non-operating +72 hours @75° C operating)





#### This testing method is broken down into two procedures.

- Procedure I (storage) exposes the system to high temperatures
  while it is turned off, and its purpose is to test the durability
  of the materials that make up the system. The chamber
  temperature is 75°C and the test duration is 96 hours.
- Procedure II (operation) is to test how the device puts up with heat while having it turned on and used.
- The chamber temperatures used in an operational cyclical test is 75°C, and the test duration is 72 hours. The temperature needs to cycle from one end to the other a minimum of three times while testing that the device functions at every point in the test.

#### 5.Low Temperature

►MIL-STD-810G Test Method 502.5 Low Temp (96 hours @ -40° C non-operating +72 hours @ -40° Coperating)





## There are two parts in this test to determine whether the system can persevere in extremely cold environment.

- Procedure I (storage) exposes the system to low temperatures while it is turned off, and its purpose is to test the durability of the materials that make up the system.
   The chamber temperature is -40°C and the test duration is 96 hours.
- Procedure II (operation) testing involves slowly cooling the device to the low temperature and leaving it at that temperature for at least two hours, checking to see that it is still functioning during that time. The chamber temperature is -40°C and the test duration is 72 hours.

MIL-STD 810								
Temperature	Operating	Low temperature Method 502.5, Procedure 2 → -20°C, 4 hours, ±3°C						
	Operating	High temperature Method 501.5, Procedure 2 $\rightarrow$ +55°C, 4 hours, ±3°C						
	Non-Operating	Non-operating low temperature Method 502.5 → -33°C, 4 hours, change rate:≦20°C/ Hour						
		Non-operating high temperature Method 501.5 Procedure 1 → +71°C, 4 hours, change rate:≦20°C/Hour						
Vileventiere	Operating	Vibration Method 514.6 → 5-500Hz, Vertical 2.20 grms, Transverse 1.62 grms, Longitudinal 2.05 grms. 40mins , x 3axis						
Vibration	Non-Operating	Non-operating Vibration Method 514.6 → 5-500Hz, Vertical 3.20Grms, 40mins , x 3axis.						
Shock	Operating	Shock Method 516.6 $\rightarrow$ 20 Grms, 10 times for each direction, 6 directions, 60 times in total 11ms, 3 axis.						
oo.k	Non-Operating	Non-operating Shock Method 516.6 $\rightarrow$ 20 Grms, 11ms, 3 axis.						
Humility		Method 507.4 , Pre-conditioning period: 23±2°C and 50±5%RH, maintain for 24 hours.  → 30°C~60°C, 85%~95%RH without condensation, 24 hours/cycle, conduct 10 cycles						
Salt Fog		Method 509.7 Salt Spray (50±5)g/L						
Sealing		IEC 60529/ IP65						
Fungus		Method 508.6						
Altitude	Operating	Method 500.5, Procedures I and II → 12,192M, (40,000 ft) for the initial cabin altitude (18.8Kpa or 2.73 Psia)						
Aidituue	Non-Operating	Method 500.5, Procedures III and IV → 15,240, (50,000 ft) for the initial cabin altitude (14.9Kpa or 2.16 Psia)						

## MIL-STD 461/1275

PCIe / 104 COMe T6 COMe T7









AV600RH-A45

THOR200-X11

THOR200-DL



Ensures function properly within electromagnetic (EM) environments and avoid releasing EM energy cause EM interference (EMI) with nearby devices.

#### **CE 102**

#### 10 kHz-30 MHz

Conducted Emissions, Radio Frequency Potentials & Power Leads, basic curve

#### **RE 102**

**30 MHz - 5 GHz** Radiated Emissions, Electric Field

#### **RE 103**

**80 MHz - 3 GHz**Radiated susceptibility,
Electric Field

when powered from a 28V supply, ensuring that electronics survive in the field when faced with input voltage spikes and surges.

Surge High 100V / 500ms **Surge Low** 

18V / 500ms

**Steady State** 

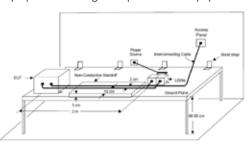
18V~33V



### MIL-STD 461

MIL-STD-461 is a military standard that establishes the control of electromagnetic interference (EMI) emissions and susceptibility characteristics of electronic,

electrical & electromechanical equipment and subsystems for military equipment. EMI encompasses any undesired signals, "noise", generated by electronic equipment. Keeping EMI under control is crucial for military applications, because if it's out of control, the military will be detected by the enemy and it might cause a great loss. To design a product that meets strict requirements, engineers should possess extensive knowledge of both electrical and mechanical design to avoid unintentional generation, propagation and reception of electromagnetic energy, which may cause unwanted effects, for example, physical damage in operational equipment.



		_																	_
Test Method Installation/Platform	CE101	CE102	CE106	CS101	CS103	CS104	CS105	CS109	CSI14	CSIIE	CS116	CS117	CSII8	RETOT	RE102	RE103	RS101	RS103	RS105
Surface Ships	Α	Α	L	Α	S	L	S	L	Α	S	Α	L	S	Α	Α	L	L	Α	L
Submarines	Α	Α	L	Α	S	L	S	L	Α	S	L	S	S	Α	Α	L	L	Α	L
Aircraft, Army (Fit Line)	Α	Α	L	Α	S	S	S		Α	Α	Α	L	Α	Α	Α	L	Α	Α	L
Aircraft, Navy	L	Α	L	Α	S	S	S		Α	Α	Α	L	Α	L	Α	L	L	Α	L
Aircraft, Air Force		Α	L	Α	S	S	S		Α	Α	Α	L	Α		Α	L		Α	
Space Systems (Launch)		Α	L	Α	S	S	S		Α	Α	Α	L			Α	L		Α	
Ground, Army		Α	L	Α	S	S	S		Α	Α	Α	S	Α		Α	L	L	Α	
Ground, Navy		Α	L	Α	S	S	S		Α	Α	Α	S	Α		Α	L	L	Α	L
Ground, Air Force		Α	L	Α	S	S	S		Α	Α	Α		Α		Α	L		Α	
Description	CE, AF Currents, Power Leads	CE, RF Currents, Power Leads	CE, Antenna Port	CS, Power Leads	CS, Antenna Port, Intermodulation	CS, Antenna Port, Rejection of Undesired Signals	CS, Antenna Port, Cross-modulation	CS, Structure Current	CS, Bulk Cable Injection (RF)	CS, Bulk Cable Injection (Impulse)	CS, Damped Sinusoidal Transients	CS, Lightning Induced Transients	CS, Personnel Borne ESD	RE, Magnetic Field	RE, Electric Field	RE, Antenna Spurious & Harmonic Outputs	RS, Magnetic Field	RS, Electric Field	RS, Transient Electromagnetic Field

- •A= Applicable; L=Limited Applicability; S=Specified in Procurement Documentation
- ▶ Tailoring of requirements permitted

(specialized limits, adjusted frequency range, alter applicability, etc.)

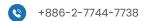
▶Each test method may include various test limits or susceptibility test levels

## **MIL-STD 461**

	MIL-STD 461 (Ground Vehicle)	MIL-STD 461/1275	MIL-STD 461/1275/704								
05100		(Aircraft)									
CE102	CE102 basic curve, 10kHz - 30 M										
	N/A	RE102-4, (10 KHz)-2.0 MHz									
RE102-4	RE102-4, (1.5 MHz ) -30.0 MHz										
	RE102-4, ( 30.0 MHz) - 5.0 GHz										
	N/A										
	RS103, ( 200 MHz ) - 3 GHz,										
RS103	RS103, (1.5 MHz) - 200 MHz, 50 V/m equal for all frequencies										
	RS 103,(3.0 GHz) - 5.0 GHz 50V/m equal for all frequencies										
	EN 61000-4-2: Air discharge: 8 k	«V,Contact discharge: (	5kV								
EN61000	EN 61000-4-3: 10V/m										
	EN 61000-4-4: Signal and DC-N										
	EN 61000-4-5: Leads vs. ground	l potential 1kV, Signal u	nd DC-Net: 0.5								
EN55022	EN 55022, Class A										
	CS101 (30HZ~150KHZ)										
CS	CS114 (10kHz~200MHz)										
	CS11550v/m										
	CS116 50v/m										
		Steady State - 20V~33V,									
		Surge Low - 18V/500ms,									
		Surge High - 100V/500ms									
	N/A	Emitted spikes									
MIL-STD-1275		Injected Voltage surges									
		Emitted voltage surges									
		Voltage ripple (2V)									
		Voltage spikes									
		Starting Operation									
		Reverse polarity									
			Load Measurements (LDC101)								
			Steady State Limits for Voltage(LDC102)								
MIL-STD-704			Voltage Distortion Spectrum (LDC103)								
			Total Ripple (LDC104)								
			Normal Voltage Transients (LDC105)								
	N/A	N/A	Power Interrupt (LDC201)								
	1,71	.,	Abnormal Steady State Limits forVoltage (LDC301)								
			Abnormal Voltage Transients (LDC302)								
			Emergency Steady State Limits forVoltage (LDC401)								
			Starting Voltage Transients (LDC501)								
			Power Failure (LDC601)								
		Phase Reversal (LDC602)									



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